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Problem Formulation. The RLF objectives are to solve the problems of a geometrical system as it evolves in time, or it is being observed in successive instants. The Geometric information in an EDF, EDF expresses the observations as spatial and temporal functions. As a result, a three dimensional time resolved expression is obtained for the geometrical information. To represent the observation functions, the EDF is decomposed into summation of their spatial and temporal components, which in turn, are represented as 1 dimensional (1-D) or 2-D spatial curves, respectively. The geometric system in an EDF can be assumed to be a one or two dimensional shape, e.g., plane, conical, cylindrical or spherical shape. This work focuses on those subjects that develop the EDF representations from given data expressed as series of 2-D shapes or shapes that have similar geometrical characteristics. A single 2-D shape is usually expressed as a set of vertices, edges, bsplines and boundary curves. On the other hand, a set of geometrical information that are inherent to the information processing techniques, e.g., characteristics of vertices, edges, bsplines and boundary curves are expressed as series of 2-D shapes by using the coordinate systems. As another example, a single 2-D shape, as a pattern object, whose geometric pattern is represented by a set of 2-D vertices, is represented by vectors. Similarly, a set of vertices is expressed by a set of vectors. Here, a typical operation that expresses a 2-D or 3-D shape by a set of vertices, edges, bsplines and boundary curves is termed a co-ordinate system transformation. Suppose that the shape represented by the set of vertices (or a set of vertices and edges) is mapped by a mapping function to a set of rectangular coordinates of the graph grid and there are coordinates {x0, y0, x1, y1,...,xm, ym). The mathematical expression, represented by a series of coordinates {x0, y0, x1, y1,...,xm, ym}, is termed a space curve. A space curve is represented as a set of vertices, edges and/or bsplines. The vertex sequence is the sequence of coordinates, {x0, y0, x1, y1,...,x

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